

RANDOM PROCESSES: 2004 EXAM SOLUTION.

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Problem 1.

(a) The process X is not Gaussian. Suppose it is, then e.g. if $d = 2$ and $r_1 = -r_2 = 1$, $p_1 = p_2 = 1/2$ then $EX_0X_1 = EX_0^2Ea + EX_0E\varepsilon_1 = 0$ implies that X_0 and X_1 are independent and thus

$$E(\varphi(X_1)|X_0) = E\varphi(X_1)$$

should hold for any function φ , such that $E|\varphi(X_1)| < \infty$. The latter fails for $\varphi(x) = x^2$:

$$E(X_1^2|X_0) = E(X_0^2a^2 + 2X_0a\varepsilon_1 + \varepsilon_1^2|X_0) = X_0^2 + 1.$$

(b) Given a , X_n is a linear combination of ε_i 's, (which are independent of a !) and hence is conditionally Gaussian. Namely

$$(1.1) \quad X_n = a^n X_0 + \sum_{i=1}^n \varepsilon_i a^{n-i},$$

i.e. $X_n = \alpha^n \varepsilon^n$, where α^n is the appropriate row vector, depending on a , and ε^n is the vector with ε_i as entries. Hence

$$\begin{aligned} E(\exp\{i\lambda\alpha^n\varepsilon^n\}|a) &= \int_{\mathbb{R}^n} \exp\{i\lambda\alpha^n x\} \frac{1}{(2\pi)^{n/2}} \exp\left\{-\sum_i x_i^2/2\right\} dx_1 \dots dx_n = \\ &\exp\left\{-\frac{1}{2}\lambda^2\|\alpha^n\|^2\right\} \quad (\text{why is the last equality correct?}) \end{aligned}$$

(c) Given a , X is a conditionally Gaussian process. The proof is by similar arguments as in (b) (α^n is a matrix this time).

(d) a is not Gaussian, conditioned on X_0^n . One may be tempted to give (wrong) positive answer, since given X_0^n , a is a linear combinations of ε_i 's. Note however that this time ε_i 's depend on the condition X_0^n ! Again if $d = 2$, $r_1 = -r_2 = 1$, $p_1 = p_2 = 1/2$, then e.g. $P(|a| \leq 0.17|X_0^n) = 0$, so that $P(a \leq x|X_0^n)$ cannot have Gaussian density. In fact the conditional distribution is lattice (discrete) as claimed below.

(e) By standard arguments $\pi_n(i) := G^i(X_0^{n-1}, X_n)$ should satisfy

$$E\left(I(a = r_i)h(X_n)|X_0^{n-1}\right) = E\left(G^i(X_0^{n-1}, X_n)h(X_n)|X_0^{n-1}\right)$$

for any test function h . Then

$$E\left(I(a = r_i)h(X_n)|X_0^{n-1}\right) = E\left(I(a = r_i)h(r_i X_{n-1} + \varepsilon_n)|X_0^{n-1}\right) = \pi_{n-1}(i) \int_{\mathbb{R}} \psi(u - r_i X_{n-1})h(u)du$$

where $\psi(x)$ is the standard Gaussian density. Similar arguments for the right hand side of the above condition and arbitrariness of h imply

$$\pi_n(i) = \frac{\pi_{n-1}(i)\psi(X_n - r_i X_{n-1})}{\sum_{j=1}^d \pi_{n-1}(j)\psi(X_n - r_j X_{n-1})}, \quad \pi_0(i) = p_i.$$

(f) No - by the same argument as in (a).

(g) Yes - by the same argument as in (b).

(h) Yes - by the same argument as in (c).

(i) a is conditionally Gaussian given X_0^n . The proof can be found in Problem 5.3 of home assignments.

(j) X_n does not converge to zero in probability: fix any constant $-1 < r < 1$

$$P(|X_n| \geq \varepsilon) = EI(|X_n| \geq \varepsilon) \geq EI(|X_n| \geq \varepsilon)I(|a| \leq r) = EP(|X_n| \geq \varepsilon|a)I(|a| \leq r)$$

Recall that X_n is conditionally Gaussian given a with zero mean and conditional variance $V_n(a) = E(X_n^2|a)$, satisfying the recursion $V_n(a) = a^2 V_{n-1}(a) + 1$, subject to $V_0 = 1$. Note that $V_n(a)$ increases and $1 \leq V_n(a) \leq (1 - r^2)^{-1}$ P -a.s. on the set $\{|a| \leq r\}$ for all $n \geq 0$. In particular

$$P(|X_n| \geq \varepsilon|a) = \int_{|x| \geq \varepsilon} \frac{1}{\sqrt{2\pi V_n}} \exp\{-x^2/(2V_n)\}dx \geq 1 - \frac{2\varepsilon}{\sqrt{2\pi V_n(a)}} \geq 1 - \frac{2\varepsilon\sqrt{1-r^2}}{\sqrt{2\pi}} := c > 0$$

So we have

$$P(|X_n| \geq \varepsilon) \geq cP(|a| \leq r) > 0, \quad \forall n$$

and clearly $P(|X_n| \geq \varepsilon) \not\rightarrow 0$ for any $\varepsilon > 0$. Hence it does not converge neither in \mathbb{L}^1 nor P -a.s. The latter means that $P(\lim_{n \rightarrow \infty} X_n = 0) < 1$. In fact $P(\lim_{n \rightarrow \infty} X_n = 0) = 0$ in this case, since

$$\{\lim_{n \rightarrow \infty} X_n = 0\} \subseteq \{\lim_{n \rightarrow \infty} |X_n - aX_{n-1}| = 0\} = \{\lim_{n \rightarrow \infty} \varepsilon_n = 0\},$$

whereas the latter set obviously has zero probability (e.g. by Borel-Cantelli lemma).

It doesn't converge in law to zero, since then it would converge to zero in probability. In fact it doesn't converge in law at all (i.e. to any random variable) - why?

(k) The solution (1.1) implies $EX_n = 0$ and so a is orthogonal to X_n for any $n \geq 0$:

$$EaX_n = Ea^{n+1}EX_0 + \sum_{i=1}^n Ea^{n-i+1}E\varepsilon_i = 0.$$

Then obviously $\widehat{E}(a|X_0^n) = 0$ and $E(a - \widehat{a}_n)^2 = Ea^2 = 1$.

(1) If a is Gaussian, then X is *conditionally* Gaussian, meaning that the generalized Kalman filter generates the required conditional expectation (see Problem 5.3 in home assignments). The filtering model is

$$\begin{aligned} a_n &= a_{n-1} \\ X_n &= X_{n-1}a_{n-1} + \varepsilon_n \end{aligned}$$

subject to (a, X_0) . The filtering equations for $\bar{a} = E(a|X_0^n) = E(a_n|X_0^n)$ and $\bar{P}_n = E[(a - \bar{a}_n)^2|X_0^n]$ are

$$\begin{aligned} \bar{a}_n &= \bar{a}_{n-1} + \frac{X_{n-1}\bar{P}_{n-1}}{X_{n-1}^2\bar{P}_{n-1} + 1}(X_n - X_{n-1}\bar{a}_{n-1}) \\ \bar{P}_n &= \bar{P}_{n-1} - \frac{X_{n-1}^2\bar{P}_{n-1}^2}{X_{n-1}^2\bar{P}_{n-1} + 1} \end{aligned}$$

subject to $\bar{a}_0 = 0$ and $\bar{P} = 1$. Note that the obtained estimate is nonlinear, as expected.

(m) Let $Q_n = \bar{P}_n^+$ (i.e. $Q_n = I(\bar{P}_n > 0)/\bar{P}_n$). Then

$$Q_n = Q_{n-1} + X_{n-1}^2 = 1 + \sum_{i=1}^n X_{i-1}^2.$$

or

$$\bar{P}_n = \frac{1}{1 + \sum_{i=1}^n X_{i-1}^2}, \quad n \geq 1.$$

Intuitively \bar{P}_n should converge to zero, since the denominator grows to infinity. We claim that \bar{P}_n converges to zero P -a.s. and thus also in probability and in law. Since $\bar{P}_n \leq 1$, this implies convergence in \mathbb{L}^p , $p \geq 1$.

Note that

$$\{\lim_{n \rightarrow \infty} \bar{P}_n \neq 0\} = \{\lim_{n \rightarrow \infty} \sum_{i=1}^n X_{i-1}^2 < \infty\} \subseteq \{\lim_{n \rightarrow \infty} X_n = 0\}.$$

Since by (j) $P(\lim_{n \rightarrow \infty} X_n = 0) = 0$, we conclude that $P(\lim_{n \rightarrow \infty} \bar{P}_n \neq 0) = 0$.

Remark: convergence P -a.s. roughly means that the square error converges to zero on any (possible) trajectory of X_n , while convergence in \mathbb{L}^1 means that the mean square error goes to zero.

Problem 2.

(a) Taking expectation from both sides of

$$\begin{aligned} dx_t &= y_t dt \\ dy_t &= -x_t dt - 2y_t(\beta dt + \sigma dW_t), \end{aligned}$$

one gets

$$\begin{aligned} d\bar{x}_t &= \bar{y}_t dt \\ d\bar{y}_t &= -\bar{x}_t dt - 2\beta\bar{y}_t dt, \end{aligned}$$

which means that on average the system behaves as the unperturbed pendulum for any $\beta > 0$. Since the initial conditions have zero mean, $Ex_t = 0$ and $Ey_t = 0$ for any $t \geq 0$.

(b) By the Ito formula

$$\begin{aligned}
dq_t &= d(x_t^2) = 2x_t dx_t = 2x_t y_t dt = 2u_t dt \\
dr_t &= d(y_t^2) = 2y_t \left(-x_t dt - 2y_t(\beta dt + \sigma dW_t) \right) + 4\sigma^2 y_t^2 dt = \\
&\quad 4(\sigma^2 - \beta)y_t^2 dt - 2x_t y_t dt - 4y_t^2 \sigma dW_t = 4(\sigma^2 - \beta)r_t dt - 2u_t dt - 4r_t \sigma dW_t \\
du_t &= d(x_t y_t) = y_t dx_t + x_t dy_t = y_t^2 dt - x_t^2 dt - 2y_t x_t(\beta dt + \sigma dW_t) = \\
&\quad r_t dt - q_t dt - 2\beta u_t dt - 2u_t \sigma dW_t
\end{aligned}$$

(c) Taking the expectation we get

$$\begin{aligned}
d\bar{q}_t &= 2\bar{u}_t dt \\
d\bar{r}_t &= 4(\sigma^2 - \beta)\bar{r}_t dt - 2\bar{u}_t dt \\
d\bar{u}_t &= \bar{r}_t dt - \bar{q}_t dt - 2\beta\bar{u}_t dt
\end{aligned}$$

or in matrix notation for $Z_t = (\bar{q}_t, \bar{r}_t, \bar{u}_t)$

$$\dot{Z}_t = \begin{pmatrix} 0 & 0 & 2 \\ 0 & 4(\sigma^2 - \beta) & -2 \\ -1 & 1 & -2\beta \end{pmatrix} Z_t$$

subject to $Z_0 = (1, 1, 0)$.

(d) The latter is a linear system with constant coefficients and its stability is completely determined by the eigenvalues of the coeff. matrix. Let $z = 4(\sigma^2 - \beta)$ for brevity. First note that $z = 0$ ($\sigma = \sqrt{\beta}$) is a "suspicious" point, for which the system has zero eigenvalue and thus is unstable.

The eigenvalues are the roots of the polynomial

$$\begin{aligned}
p(\lambda) &= \det \begin{pmatrix} -\lambda & 0 & 2 \\ 0 & z - \lambda & -2 \\ -1 & 1 & -2\beta - \lambda \end{pmatrix} = \\
&= -\lambda \left\{ -(z - \lambda)(2\beta + \lambda) + 2 \right\} + 2(z - \lambda) = \lambda \left\{ (z - \lambda)(2\beta + \lambda) - 2 \right\} + 2(z - \lambda)
\end{aligned}$$

Assume that $z > 0$, then

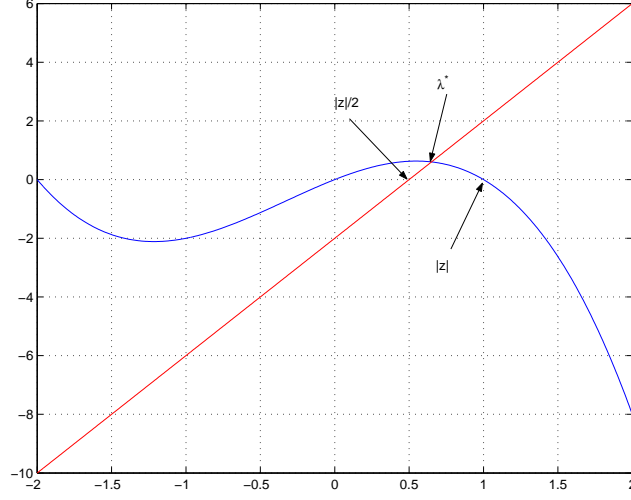
$$\begin{aligned}
p(\lambda) &= \lambda \left\{ (|z| - \lambda)(2\beta + \lambda) - 2 \right\} + 2(|z| - \lambda) = \\
&\quad \lambda \left\{ (|z| - \lambda)(2\beta + \lambda) \right\} + 2(|z| - 2\lambda) := p_1(\lambda) - p_2(\lambda)
\end{aligned}$$

The polynomial $p_1(\lambda)$ has roots at 0, $|z|$, $-2\beta < 0$ and decreases (increases) to $-\infty$ (∞) as $\lambda \rightarrow \infty$ ($\lambda \rightarrow -\infty$). The line $p_2(\lambda) = -2(|z| - 2\lambda)$ crosses the abscissa axis at $|z|/2 > 0$ and has a positive slope. Hence it crosses $p_1(\lambda)$ at some $\lambda^* \in (|z|/2, |z|)$ - see Figure. So the system has a positive root and is unstable for all $z > 0$, i.e. for all $\sigma^2 \geq \beta$. By the same arguments it is clear that the real root λ^* is negative when $z < 0$ and $\lambda^* \in (z/2, 0)$. Expand the polynomial $p(\lambda)$, when $z < 0$, i.e. $z = -|z|$

$$-p(\lambda) = \lambda^3 - \lambda^2(z - 2\beta) - \lambda(2\beta z - 4) - 2z = \lambda^3 + \lambda^2(|z| + 2\beta) + \lambda(2\beta|z| + 4) + 2|z|$$

Assume that the other two roots are complex (conjugate), denoted by λ' and $\bar{\lambda}'$ and recall that

$$-b_1 = \lambda^* + 2\Re\{\lambda'\}$$

FIGURE 1. Case $z > 0$

where b_1 is the polynomial coefficient corresponding to power two. Since $\lambda^* < 0$

$$-(|z| + 2\beta) = -|\lambda^*| + 2\Re\{\lambda'\} \implies 2\Re\{\lambda'\} = -(|z| + 2\beta) + |\lambda^*|$$

Recall that $\lambda^* \in (-|z|/2, 0)$ in this case, so $\Re\{\lambda'\} \leq -\beta - |z|/2 < 0$, i.e. the system is stable.

Suppose now that the roots λ_1 and λ_2 are real. Recall that

$$-b_3 = \lambda^* \lambda_1 \lambda_2 = -|\lambda^*| \lambda_1 \lambda_2$$

where $b_3 = 2|z|$ is the free coefficient. Then λ_1 and λ_2 have the same sign. Using again

$$-b_1 = \lambda^* + \lambda_1 + \lambda_2 \implies \lambda_1 + \lambda_2 = -(|z| + 2\beta) + |\lambda^*|$$

we conclude that $\lambda_1 + \lambda_2 < -2\beta - |z|$, and thus both roots are negative.

In summary, $\sigma \geq \sqrt{\beta}$ destabilizes the pendulum, while for $\sigma < \sqrt{\beta}$ it remains stable.

Remark: the same conclusion may be obtained faster via Routh-Hurwitz Theorem.

Remark: a much more delicate analysis shows that σ may exceed $\sqrt{\beta}$, while stability is preserved in e.g. P -a.s. sense.